



Technical Brief

NVIDIA Jetson TK1 Development Kit

*Bringing GPU-accelerated
computing to Embedded Systems*

V1.0

Table of Contents

.....	1
Introduction	4
NVIDIA Tegra K1 – A New Era in Mobile Computing	5
Kepler GPU in Tegra K1	6
Jetson TK1 Development Kit	7
Hardware Platform	7
Software Platform	7
VisionWorks Computer Vision Toolkit	8
Jetson TK1 – Delivering Exceptional Performance and Power Efficiency	9
Conclusion	11
Appendix	12
Jetson K1 Platform Peripheral and IO ports	12
Jetson K1 Development Platform Power Consumption	12
Document Revision History	14

Introduction

GPU-accelerated computing is rapidly increasing the velocity of innovation in the fields of science, medicine, finance and engineering. GPU-accelerated computing is the use of a graphics processing unit (GPU) together with a CPU to accelerate scientific, engineering, and enterprise applications. Pioneered by NVIDIA, GPU-accelerated computing offers unprecedented application performance by offloading compute-intensive portions of the application to the GPU, while the remainder of the code still runs on the CPU. From a user's perspective, applications simply run significantly faster.

NVIDIA also defined the **NVIDIA CUDA** parallel programming platform to standardize and refine GPU-accelerated computing. CUDA has become the world's leading GPU computing platform used by millions of users for high-performance computing across a range of industries and sciences, including usage in many of the top supercomputers in the world. GPU computing delivers unprecedented levels of performance speedups by parallelizing application workloads and running them on the GPU.

NVIDIA's Fermi and Kepler GPUs have already redefined and accelerated High Performance Computing (HPC) capabilities in areas such as seismic processing, biochemistry simulations, weather and climate modeling, computational finance, computer aided engineering, computational fluid dynamics and data analysis. The Kepler Compute architecture together with NVIDIA's CUDA parallel programming platform delivers tremendous performance speedup not only for numerous high-performance computing applications, but also for applications such as speech recognition, live video processing, computer vision, augmented reality, and of course computer gaming.

Embedded Computing is the next frontier where GPUs can help accelerate the pace of innovation and deliver significant benefits in the fields of computer vision, robotics, automotive, image signal processing, network security, medicine, and many others. The **Jetson TK1 Development Kit** is specifically designed to enable rapid development of GPU-accelerated embedded applications, bringing significant parallel processing performance and exceptional power efficiency to embedded applications.

The Jetson TK1 Development kit is designed around the revolutionary **192-core NVIDIA Tegra K1** mobile processor. Tegra K1 is based on the same NVIDIA Kepler GPU architecture used in supercomputers and High Performance Computing systems around the world. The Jetson Development Kit delivers a fully functional NVIDIA CUDA platform and includes the Board Support Package, **CUDA 6**, **OpenGL 4.4**, and the **NVIDIA VisionWorks** toolkit. With a complete suite of development and profiling tools, plus out-of-the-box support for cameras and other peripherals, the NVIDIA Jetson TK1 Development Kit is the ideal development platform to shape a brand new future for Embedded Computing.

Note: Details on Jetson TK1 IO ports and Platform Power is provided in the Appendix

NVIDIA Tegra K1 – A New Era in Mobile Computing

NVIDIA's latest and most advanced mobile processor, the **Tegra® K1**, creates a major discontinuity in the state of mobile graphics by bringing the powerful **NVIDIA Kepler™ GPU** architecture to mobile and delivering tremendous visual computing capabilities and breakthrough power efficiency. The NVIDIA Tegra K1 mobile processor is designed from the ground up to create a major discontinuity in the capabilities of mobile processors, and delivers the industry's fastest and most power efficient implementation of mobile CPUs, PC-class graphics, and advanced GPU-accelerated computing capabilities.

Some of the key features of the Tegra K1 SoC (System-on-a-Chip) architecture are:

- **4-PLUS-1 Cortex A15 “r3”** CPU architecture that delivers higher performance and is more power efficient than the previous generation.
- **Kepler GPU architecture** that utilizes **192 CUDA cores** to deliver advanced graphics capabilities, GPU computing with **NVIDIA CUDA 6** support, breakthrough power efficiency and performance for the next generation of gaming and GPU-accelerated computing applications.
- **Dual ISP Core** that delivers 1.2 Giga Pixels per second of raw processing power supporting camera sensors up to 100 Megapixels.
- **Advanced Display Engine** that is capable of simultaneously driving both the 4K local display and a 4K external monitors via HDMI
- Built on the TSMC **28 nm HPM** process to deliver excellent performance and power efficiency.

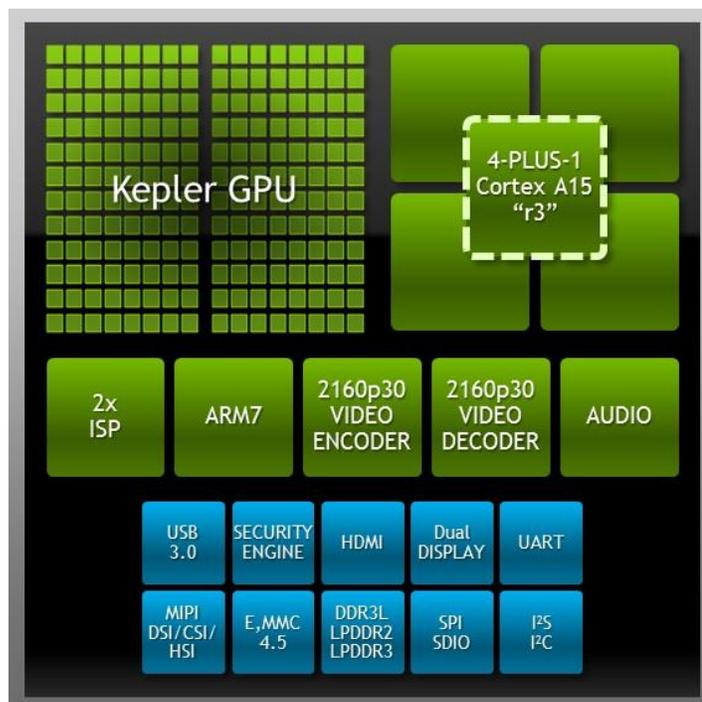


Figure 1 NVIDIA Tegra K1 Mobile Processor

Kepler GPU in Tegra K1

The Kepler GPU in Tegra K1 is built on the same high performance, energy efficient Kepler GPU architecture that is found in our high-end GeForce, Quadro, and Tesla GPUs for graphics and computing. As a result, Tegra K1 is the only mobile processor that supports **CUDA 6** for computing and full desktop **OpenGL 4.4** for graphics. Kepler delivers the most advanced graphics for mobile graphics applications, and is the first modern mobile GPU capable of supporting all the GPU compute APIs.

Tegra K1 with the Kepler GPU architecture is a parallel processor capable of over **300 GFLOPS** of 32-bit floating point computations. Tegra K1 is also very power efficient and delivers almost fifty percent higher performance per watt compared to competing mobile processors. More importantly, Tegra K1's support of CUDA and desktop graphics APIs means that much of your existing compute and graphics software will port quite easily to Jetson TK1.

	TEGRA K1 Kepler Graphics	GEFORCE GTX 770
OpenGL ES 3.1	✓	✓
OpenGL 4.4	✓	✓
DX12	✓	✓
Tessellation	✓	✓
CUDA 6.0	✓	✓

Figure 2 Tegra K1's Kepler GPU supports the feature set found in high-end NVIDIA GPUs

The Kepler GPU delivers the graphics features, rich APIs, and compute architecture of its desktop counterpart, and has additional power optimizations for mobile usage. The Kepler GPU in Tegra K1 is a significant milestone in the history of computing and computer graphics and will drive a revolutionary change in mobile visual computing. More details on Tegra K1 and its Kepler GPU are provided in the [Tegra K1 whitepaper](#).

Jetson TK1 Development Kit



Figure 3 Jetson TK1 Development board Top View

Hardware Platform

The Jetson TK1 development Kit is a 5" wide by 5" long PCB with a Tegra K1 processor, 2 GB of RAM, 16GB of on-board storage and numerous peripherals and IO ports (see Appendix). To enable development of computer vision and other camera based embedded applications, Jetson K1 is capable of supporting multiple cameras through a variety of interfaces. The USB 3.0 and Gigabit Ethernet ports can be used to hook up cameras that communicate via these interfaces. In addition, the PCIe x1 port on the PCB can be used to connect an additional camera via an Ethernet to PCIe adapter.

The CSI 1x4 and 1x1 buses available through the expansion port can be used to feed camera images directly into the Image Signal Processor (ISP) on Tegra K1 (bypassing memory), for direct image processing.

Software Platform

The Jetson TK1 Development Kit runs Linux for Tegra (L4T), a modified Ubuntu 14.04 Linux distribution provided by NVIDIA. The software provided by NVIDIA includes the Board Support Package (BSP) and the software stack that includes CUDA 6 Toolkit, OpenGL 4.4 drivers and the NVIDIA VisionWorks Toolkit.

VisionWorks Computer Vision Toolkit

Many of the interesting embedded computing domains that Jetson TK1 will support rely on computer vision. Jetson TK1 supports NVIDIA's new [VisionWorks Computer Vision Toolkit](#). VisionWorks is an SDK that provides a rich set of algorithms optimized for NVIDIA CUDA-capable GPUs and SOCs such as Tegra K1, giving you the power to realize CV applications quickly on a scalable and flexible platform.



The core VisionWorks algorithms are engineered for solutions in advanced driver assistance systems (ADAS), augmented reality (AR), computational photography, human-machine interaction (HMI), and robotics. The VisionWorks Toolkit includes libraries of algorithms and primitives to enable highly optimized pipelines on Tegra K1, example code, and full documentation.

“Having the level of performance and energy efficiency Jetson TK1 offers can potentially support the development of robots with real-time object recognition and compelling autonomous navigation capabilities”

***- Chris Jones,
Director of Strategic Technology Development
iRobot Corporation***

Jetson TK1 – Delivering Exceptional Performance and Power Efficiency

The architecture of the Kepler GPU in Tegra K1 is virtually identical to the Kepler GPU architecture used in high-end systems, but also includes a number of optimizations for mobile system usage to conserve power and deliver industry-leading mobile GPU performance. While the highest-end Kepler GPUs in desktop, workstation, and supercomputers include up to 2880 single-precision floating point CUDA cores and consume a few hundred watts of power, the Jetson TK1 platform with Tegra K1 includes 192 CUDA cores and consumes significantly lower power.

Note that the Tegra K1 Kepler GPU has more cores than many entry-level to mainstream desktop GPUs of just a few years ago. Delivering higher power efficiency and much lower platform power consumption, the Jetson TK1 platform is ideally suited for applications in the embedded space that require exceptional power efficiency, low thermal dissipation and significantly higher performance than current FPGA and x86-based embedded solutions.

“Tegra K1 can change what’s possible in the rugged and industrial embedded market. We expect to be able to offer solutions in the sub-10 watt space that previously consumed 100 watts or more.”

**- Simon Collins, Product Manager
GE Intelligent Platforms**

When compared to current generation mobile processors, the Tegra K1 powered Jetson TK1 platform delivers almost 2.5x the peak performance of competing mobile processors. When limited to match the power consumption of competing mobile processors, Tegra K1 delivers almost 50% higher performance per Watt.

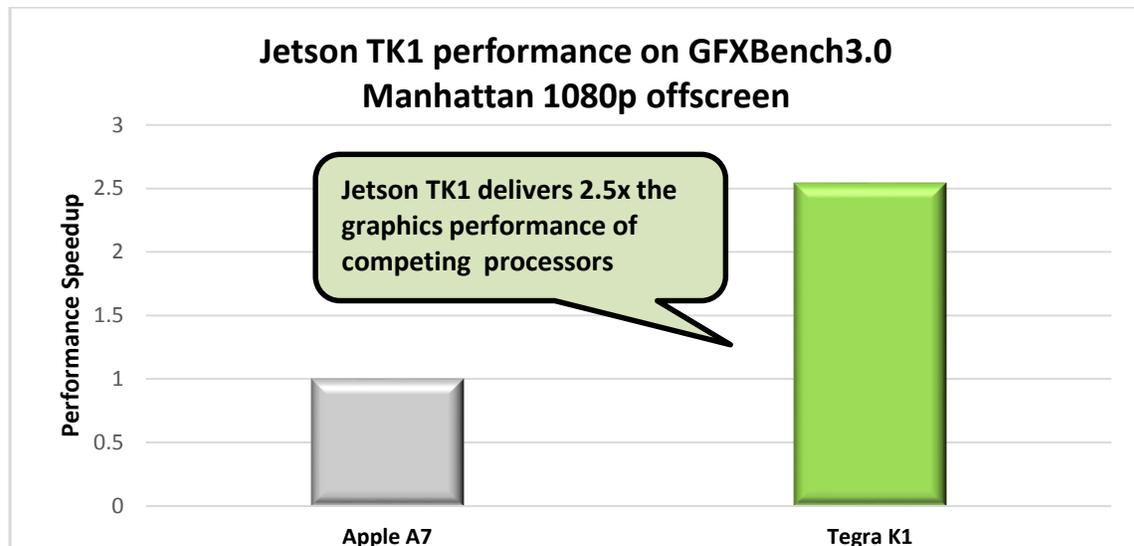


Figure 4 Jetson TK1 delivers 2.5X higher graphics performance than competing processors¹

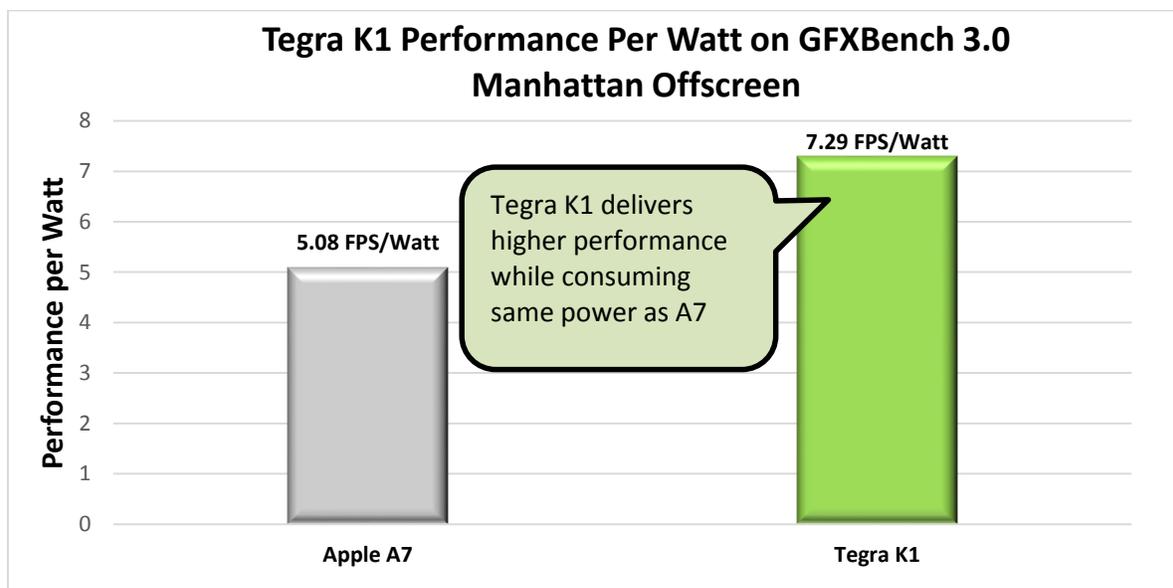


Figure 5 Tegra K1 delivers almost 1.5X performance per watt compared to Apple A7²³

¹ Tegra K1 performance measured on Jetson TK1 platform running Linux for Tegra using Linux version of GFXBench 3.0. Apple A7 performance measured on iPhone 5S running iOS 7.1

² Tegra K1 performance was measured by constraining Tegra K1 AP+DRAM power to match the AP+DRAM power consumption of iPhone 5S while running GFXBench3.0 Manhattan 1080p offscreen test.

³ Tegra K1 Performance per watt represented in this chart were collected on a mobile optimized Tegra K1 platform (that uses LPDDR3, smart panel, and other mobile optimized platform components). Jetson TK1 platform is not optimized for mobile power levels.

Conclusion

The NVIDIA Jetson TK1 Development kit is the world's first mobile supercomputer for embedded systems and opens the door for embedded system designs to harness the power of GPU-accelerated computing. Jetson TK1 will enable a new generation of applications for computer vision, robotics, medical imaging, automotive, and many other areas.

Powered by the revolutionary 192-core NVIDIA Tegra K1 mobile processor, the Jetson platform delivers over 300 GFLOPS of performance that is almost three times more than any similar embedded platform. The fully programmable 192 CUDA cores in Tegra K1 along with CUDA 6 Toolkit support makes programming on Jetson TK1 much easier than on FPGA, Custom ASIC, and DSP processors that are commonly used in current embedded systems. The CUDA programming model is used by over 100,000 developers at over 8,000 institutions worldwide. The Jetson TK1 Developer Kit comes with full support of the CUDA 6.0 developer tool suite, including debuggers and profilers, to allow development of powerful embedded applications.

Jetson TK1 fast tracks embedded computing into a future where machines interact and adapt to their environments in real time, and deliver whole new experiences in various fields such as robotics, augmented reality, computational photography, human-computer interface, and advanced driver assistance systems.

Appendix

Jetson K1 Platform Peripheral and IO ports

Standard ports on Jetson TK1 Development board
<ul style="list-style-type: none"> • 1 Half mini-PCIE slot
<ul style="list-style-type: none"> • 1 Full-size SD/MMC connector
<ul style="list-style-type: none"> • 1 Full-size HDMI port
<ul style="list-style-type: none"> • 1 USB 2.0 port, micro AB
<ul style="list-style-type: none"> • 1 USB 3.0 port, A
<ul style="list-style-type: none"> • 1 RS232 serial port
<ul style="list-style-type: none"> • 1 ALC5639 Realtek Audio Codec with Mic in and Line out
<ul style="list-style-type: none"> • 1 RTL8111GS Realtek GigE LAN
<ul style="list-style-type: none"> • 1 SATA data port
<ul style="list-style-type: none"> • SPI 4MByte boot flash
Additional ports available via Expansion port
<ul style="list-style-type: none"> • DP/LVDS
<ul style="list-style-type: none"> • Touch SPI
<ul style="list-style-type: none"> • 1x4 + 1x1 CSI-2
<ul style="list-style-type: none"> • GPIOs, UART, HSIC and I2C

Table 1 Peripheral and IO Ports on Jetson TK1 Development board

Jetson TK1 Development Platform Power Consumption

The Jetson TK1 Development platform is primarily designed to enable the development of GPU-accelerated embedded applications and is not optimized to deliver the low power consumption required on mobile devices such as tablets and smartphones.

Being a development platform, the Jetson TK1 has numerous hardware, IO, and peripheral interfaces that add to the total platform power consumption. The core software package is optimized to deliver the performance required for embedded applications such as computer vision, robotics, and image processing. For example, mobile platforms that run on battery power may use power-efficient LPDDR3 memory, smart panel displays, PMICs, and other low power components. The Jetson development platform is designed to run on AC power and therefore uses standard DDR3L memory, Ethernet adapters, standard HDMI, and other platform components that are not optimized for low power.

Due to these design choices, the Jetson TK1 development platform should not be used evaluate the power efficiency of the Tegra K1 mobile processor for mobile implementations and applications. Developers and OEMs who want to power profile applications for mobile are encouraged to contact our NVIDIA Developer Relations team to request mobile platform support. In addition, the Developer Relations team can provide guidance for power efficiency optimization for mobile and embedded applications. The following table breaks down the Jetson TK1 platform power consumption at idle state and at peak performance.

Platform Component	Idle State Platform Power (milli-Watts)	Platform power when AP+DRAM is constrained to Apple A7 power when running GFXBench 3.0 ⁴ (milli-Watts)	Platform power when delivering peak GFXBench 3.0 Performance(milli-Watts)
AP+DRAM ⁵	660	3660 ⁶	6980
Power consumed by Platform components such as Fan, HDMI, PCIE, SATA and others	2080	2090	2090
SoC Voltage regulator Efficiency loss	280	960	1790
Total Power at DC input of the board	3020	6710	10860
AC to DC conversion loss (15%) ⁷	450	1180	1630
Power consumed at AC outlet ⁸	3470	7890	12490

Table 2 Jetson TK1 Development Platform Power

⁴ Power was measured while running GFXBench 3.0 Manhattan 1080p Offscreen test

⁵ Jetson TK1 uses standard DDR3L memory and the L4T processor governors are not optimized for power efficiency. Conclusions based on these numbers on Tegra K1 power consumption for mobile applications will be incorrect.

⁶ Apple A7 consumed 2560 mW to deliver 13 fps on iPhone 5S. An equivalent Tegra K1 mobile platform consumes 2605 mW to deliver 1.45x higher performance. Since Jetson uses DDR3L and OS is not tuned for mobile, it consumes 3658 mW to deliver an equivalent 1.45x performance advantage over Apple A7.

⁷ AC to DC power conversion efficiency of the power adapter will have some variance that is also influenced by the power consumed by the board.

⁸ AC power meters may have considerable measurement variances and it is recommended that power be measured at the DC power input of the board.

Document Revision History

- Initial release 1.0

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